

CDIL Interface

The Communications Desktop Integration Library (CDIL) is a small library for Windows and Macintosh applications that need to communicate with Newton OS devices. Operations are provided via a C language application program interface (API). The data exchanged is free-form. That is, the CDIL does not impose any sort of data format, nor does it imply any high, or application, level protocols. All it provides is a stream-based communications API for sending data to and receiving data from a Newton device. This API turns around and works with transport specific APIs (such as ADSP, TCP/IP, and MNP) to transfer the data.

About the CDIL

The CDIL provides a pipe between a Windows or Macintosh desktop computer and a Newton device. The CDIL uses the passive listener model. In this model the desktop application sets up the pipe, and waits for the Newton device to initiate a connection. Once the connection is set up, both sides can read and write bytes through the pipe, and terminate the connection.

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CDIL Compatibility

The following changes have been made:

<code>kCDIL_Uninitialized</code>	This state previously identified a pipe that had been created but had never been used. Now it identifies a NULL (non-created) pipe.
<code>kCDIL_InvalidConnection</code>	This state no longer exists.
<code>kCDIL_Startup</code>	This state no longer exists.
<code>kCDIL_Listening</code>	This state is unchanged.
<code>kCDIL_ConnectPending</code>	This state is unchanged.
<code>kCDIL_Connected</code>	This state is unchanged.
<code>kCDIL_Busy</code>	This state no longer exists.
<code>kCDIL_Aborting</code>	This state no longer exists.
<code>kCDIL_Disconnected</code>	This state used to identify a pipe that used to be connected, but is no longer. Now it identifies any unconnected pipe, even if it's never been used before.
<code>kCDIL_Userstate</code>	This state no longer exists.
<code>CommErr</code>	Replaced by <code>DIL_Error</code>.
<code>CDinitCDIL</code>	Renamed to <code>CD_Startup</code>.
<code>CDDisposeCDIL</code>	Renamed to <code>CD_Shutdown</code>.
<code>CDCreateCDILObject</code>	Replaced by <code>CD_CreateXXX</code> suite of functions.
<code>CDDisposeCDILObject</code>	Renamed to <code>CD_Dispose</code>.
<code>CDPeInit</code>	Replaced by <code>CD_CreateXXX</code> suite of functions.
<code>CDPeDisconnect</code>	Renamed to <code>CD_Disconnect</code>.
<code>CDPeListen</code>	Renamed to <code>CD_StartListening</code>. Function returns immediately; there is no asynchronous operation, so the

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	<i>timeout</i> , <i>completionHook</i> , and <i>refCon</i> parameters have been removed.
CDPi peAccept	Renamed to <code>CD_Accept</code> .
CDPi peAbort	Removed.
CDPi peRead	Renamed to <code>CD_Read</code> . The <i>eom</i> , <i>swapSize</i> , <i>destEncoding</i> , <i>completionHook</i> , and <i>refCon</i> parameters represent functionality that is no longer available and have been removed.
CDBytesInPipe	Renamed to <code>CD_BytesAvailable</code> . Only the reporting of bytes in the input buffer is supported, so the direction parameter has been removed.
CDPi peWrite	Renamed to <code>CD_Write</code> . The <i>eom</i> , <i>swapSize</i> , <i>destEncoding</i> , <i>completionHook</i> , and <i>refCon</i> parameters represent

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	functionality that is no longer available and have been removed.
CDI dl e	Renamed to CD_I dl e.
CDGet Pi peSt at e	Renamed to CD_Get St at e.
CDS et Pi peSt at e	Removed. User states are no longer supported.
CDEncrypt Funct i on	Removed. Encryption is no longer supported at the CDIL level.
CDDecrypt Funct i on	Removed. Encryption is no longer supported at the CDIL level.
CDGet Conf i gStr	Removed. Configuration parameters are no longer necessarily specified via a configuration string.
CDGet Port St r	Removed. Configuration parameters are no longer necessarily specified via a configuration string.
CDGet Ti meout	Removed. Timeout values are no longer pipe state variables.
CDS et Appl i cat i on	Removed. The CDIL no longer needs the application's HI NSTANCE handle.
CDFl ush	Removed. This functionality could not be guaranteed for all transport services.
CDPad	Removed. This functionality was not required at the CDIL level.
CDS et PadSt at e	Removed. This functionality was not required at the CDIL level.

Using the CDIL

Creating a CDIL Session

You must bracket all calls to CDIL functions between calls to CD_St ar t up and CD_Shut down. You create a session by passing a pointer to a pipe object, a CD_Handl e *, to one of the pipe creation functions: CD_Creat eADSP, CD_Creat eMNPSeri al , CD_Creat eTCP, and CD_Creat eCTB. These functions create a

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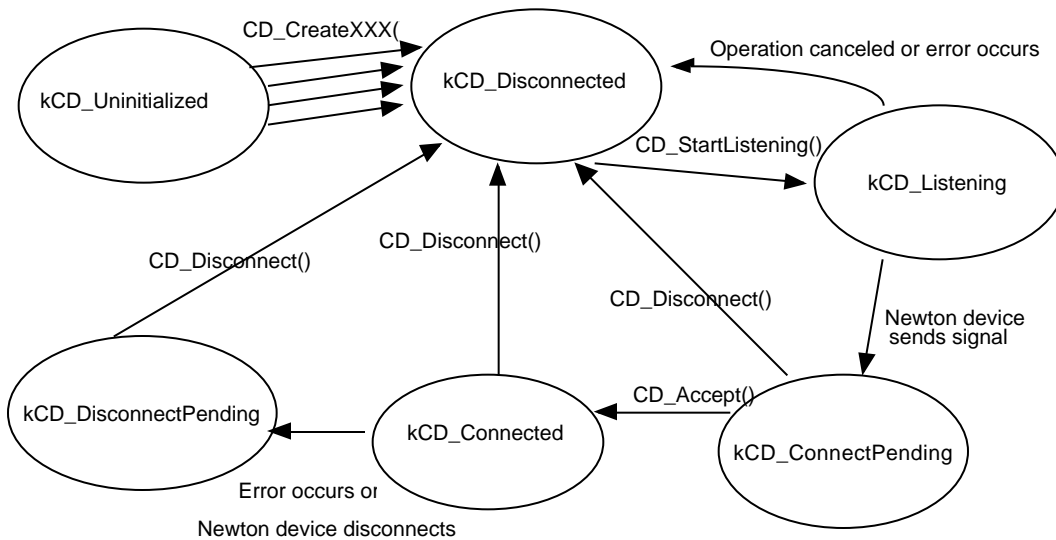
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connection with the Newton device using the requested communication service: AppleTalk, MNP Serial, TCP, or a Macintosh communication tool, respectively. All of these connection services are available in Mac OS, only the TCP and MNP Serial option are available in Windows.

Each pipe creation function has an associated checking function: `CD_CheckADSP`, `CD_CheckMNPSerial`, `CD_CheckTCP`, and `CD_CheckCTB`. These functions test to see if the appropriate service is available. They are however only an indication of whether the respective pipe creation function will succeed. They check to see if the library can be loaded and initialized, but you cannot determine if the connection attempt will succeed until you try. These functions allow an application to build a dynamic set of connection options for the user to choose from.

Once you have created a pipe to the Newton device, it is in the `kCD_Disconnected` state. You must set it to listening mode with the `CD_StartListening` function, moving it to the `kCD_Listening` state. Once in this mode, the pipe listens for a connection request from a Newton OS device. When such a request is registered, the pipe is placed in the `kCD_ConnectionPending` state by the CDIL. You should detect this condition, and call `CD_Accept` to establish the connection. `CD_Accept` puts the pipe in the `kCD_Connected` state. In this state, you can read and write bytes through the pipe.

The CDIL can thus be seen as a finite state machine. The state diagram is shown in Figure 2-1. You can use the `CD_GetState` function to determine the current state of the pipe.

Figure 2-1 CDIL state diagram

Terminating a CDIL Session

You can terminate a CDIL session at any time by calling `CD_Disconnect`. This places the pipe in the `kCD_Disconnected` state, and you are then able to attempt to start a new session by calling `CD_StartListening`. The connection can also be broken by the Newton device at any point, or fail due to some sort of error. If the connection is broken by the Newton device, or due to error, the pipe is also placed in the `kCD_Disconnected` state, unless it is presently in the `kCD_Connected` state. In that case, the pipe is placed in the `kCD_DisconnectPending` state where you can still read any buffered bytes.

When you no longer need the pipe object call `CD_Dispose` to free any allocated resources.

Reading and Writing Through the Pipe

You can write to a pipe with the `CD_Write` function so long as it is in the `kCD_Connected` state. The data is then buffered for you, and sent down the pipe at the next call to either `CD_FlushOutput`, `CD_Idle`, `CD_Read`, `CD_Disconnect`, or `CD_BytesAvailable`. The call to `CD_Write` can timeout. Each pipe has an associated timeout period, which defaults to 30 seconds. If the data cannot be sent within that period, `CD_Write` returns a `kCD_Timeout` error. You can set the timeout period with `CD_SetTimeout`; timeouts are set on a per pipe basis.

You can read data from the pipe with the `CD_Read` function so long the pipe is in either the `kCD_Connected` or `kCD_DisconnectPending` states. You specify how many bytes you wish `CD_Read` to get. `CD_Read` then blocks until that many bytes are available, or the call to `CD_Read` times out. Using the `CD_BytesAvailable` function, you can determine whether `CD_Read` would block.

As data is received from the Newton device, it is buffered by the CDIL at every possibility. You can explicitly allow the CDIL to buffer data by calling `CD_Idle`. This buffering is also performed by other CDIL functions, such as `CD_BytesAvailable`, since they present the CDIL with the opportunity to buffer this data. The underlying communication service may have a fixed-size buffer, in which case, if the Newton sends data too much data, the data could be lost. For this reason, you should call `CD_Idle` frequently to allow the CDIL to buffer the data.

Error Handling

Almost all CDIL functions return an error code. The code `kDIL_NoError`, which equals 0, indicates success. The functions descriptions in “CDIL Reference” (page 2-9) list the error codes each particular function could return if an error occurs. If an error occurs in one of the transports that the CDIL uses to implement its pipe, TCP for example, the `kCD_PlatformError` code is returned. In this case, you can call `CD_GetPlatformError` to retrieve the error code returned by the particular transport.

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Code Example

The code in Listing 2-1 shows the skeleton of a CDIL session, without error checking.

Listing 2-1 A CDIL code example

```
CD_Handle pipe;
CD_State state;
char dataBuffer[256];
long count;

CD_Startup(); // Initialize the library
CD_CreateADSP(&pipe, NULL, NULL); // Create a connection object
CD_StartListening(pipe); // Have that object listen for a
// connection from a Newton device

while (CD_GetState(pipe) == kCD_Listening) //Wait for a connect request
{
    // If you are displaying a dialog box telling the user to
    // initiate a connection from a Newton OS device, you could
    // check for clicks on a Cancel button here.
}
if (CD_GetState(pipe) == kCD_ConnectPending)
{
    CD_Accept(pipe); // Accept the connect request
    MyFnToGetDataToSend(dataBuffer);
    CD_Write(pipe, dataBuffer, sizeof(dataBuffer));
    // This step is optional. We'd execute it if we wanted to
    // ensure that there were 100 bytes available before calling
    // CD_Read, which would otherwise block.
    do
    {
        CD_Idle(pipe);
        CD_BytesAvailable(pipe, &count);
        // You could check for clicks on menus or buttons, or call
        // WaitNextEvent here.
    }
    while (count<100);
    CD_Read(pipe, dataBuffer, 100); // Assumes we expect 100 bytes back
    CD_Disconnect(pipe); // Break the connection.
}
CD_Dispose(pipe); // Delete the pipe object
CD_Shutdown(); // Close the library
```


CDIL Reference

Type Definitions

CD_Handle A pipe object.

Constants

CDIL States

These values are returned by CD_GetState:

kCD_Uninitialized	The pipe has not been initialized.
kCD_Disconnected	The pipe has just been created, or it has been passed to CD_Disconnect.
kCD_Listening	The pipe is listening for a connection request from a Newton device.
kCD_ConnectPending	The pipe has received a connection request from a Newton device.
kCD_Connected	The pipe is fully connected to a Newton device and can be used for data exchange.
kCD_DisconnectPending	The connection has been broken on the other end. Either the Newton device has disconnected, or a communications or network error has occurred. In this state, any buffered data can still be retrieved. The buffered data will be flushed when you call CD_Disconnect.

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Timeout Intervals

These values can be used for the *timeoutInSecs* parameter to `CD_SetTimeout`:

`kCD_DefaultTimeout` **The default timeout period of 30 seconds.**
`kCD_NoTimeout` **No timeout; calls to `CD_Read` and `CD_Write` do not timeout.**

Error Codes

<code>kDI_L_NoError</code>	(0)
<code>kDI_L_ErrorBase</code>	(-98000)
<code>kDI_L_OutOfMemory</code>	(<code>kDI_L_ErrorBase</code> - 1)
<code>kDI_L_InvalidParameter</code>	(<code>kDI_L_ErrorBase</code> - 2)
<code>kDI_L_InternalError</code>	(<code>kDI_L_ErrorBase</code> - 3)
<code>kDI_L_ErrorReadingFromPipe</code>	(<code>kDI_L_ErrorBase</code> - 4)
<code>kDI_L_ErrorWritingToPipe</code>	(<code>kDI_L_ErrorBase</code> - 5)
<code>kDI_L_InvalidHandle</code>	(<code>kDI_L_ErrorBase</code> - 6)
<code>kCD_ErrorBase</code>	(<code>kDI_L_ErrorBase</code> - 200)
<code>kCD_CDILNotInitialized</code>	(<code>kCD_ErrorBase</code> - 1)
<code>kCD_ServiceNotSupported</code>	(<code>kCD_ErrorBase</code> - 2)
<code>kCD_BadPipeState</code>	(<code>kCD_ErrorBase</code> - 3)
<code>kCD_Timeout</code>	(<code>kCD_ErrorBase</code> - 4)
<code>kCD_PipeDisconnected</code>	(<code>kCD_ErrorBase</code> - 5)
<code>kCD_IndexOutOfRange</code>	(<code>kCD_ErrorBase</code> - 6)
<code>kCD_BufferTooSmall</code>	(<code>kCD_ErrorBase</code> - 7)
<code>kCD_PlatformError</code>	(<code>kCD_ErrorBase</code> - 8)
<code>/* Windows-specific error codes */</code>	
<code>kCD_TCPCantFindLibraryFns</code>	(<code>kCD_ErrorBase</code> - 20)
<code>kCD_TCPIInsufficientVersion</code>	(<code>kCD_ErrorBase</code> - 21)
<code>kCD_TCPNoSockets</code>	(<code>kCD_ErrorBase</code> - 22)

Functions

CD_Startup

DILError_t CD_Startup()

Initializes the CDIL library.

return value An error code.

DISCUSSION

This call makes sure that any low-level transport layers (for example: ADSP, TCP/IP, MNP) are available and properly initialized. If none are available or none can be initialized, this function returns an error.

This function is usually called once at the start of your program. However, you can call it as many times as you want as long as you call `CD_Shutdown` an equal number of times.

ERROR CODES

`kCD_PlatformError`
`kCD_OutOfMemory`

CD_Shutdown

DILError_t CD_Shutdown()

Closes any transport layers opened and initialized in `CD_Startup`, and closes and disposes of all open pipes.

return value An error code.

DISCUSSION

This function must be called once for every time you called `CD_Startup`. Usually, you just call it once at the end of your program. However, you can call it as many times as you want, as long as you don't call it more times that you've called `CD_Startup`. If this is the last call to `CD_Shutdown`, then all memory allocated by the CDIL since `CD_Startup` was called is deallocated.

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ERROR CODES

kCD_CDILNotInitialized
kCD_PlatformError

CD_CheckADSP

DILError CD_CheckADSP()

Determines whether the ADSP service is available.

return value An error code.

DISCUSSION

This function provides an indication of whether a call to `CD_CreateADSP` will succeed or fail.

ERROR CODES

kCD_CDILNotInitialized
kCD_PlatformError
kCD_ServiceNotSupported

CD_CheckCTB

DILError CD_CheckCTB(const char* *toolName*)

Determines whether the CTB service is available.

toolName The name of the tool as a C string.

return value An error code.

DISCUSSION

This function provides an indication of whether a call to `CD_CreateCTB` will succeed or fail.

ERROR CODES

kCD_CDILNotInitialized
kCD_PlatformError
kCD_ServiceNotSupported
kDIL_InvalidParameter

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CD_CheckMNPSerial

DI L_Error CD_CheckMNPSerial ()

Determines whether the MNP service is available.

return value **An error code.**

DISCUSSION

This function provides an indication of whether a call to CD_CreateMNPSerial will succeed or fail.

ERROR CODES

kCD_CDILNotInitialized
kCD_PlatformError
kCD_ServiceNotSupported

CD_CheckTCP

DI L_Error CD_CheckTCP()

Determines whether the TCP service is available.

return value **An error code.**

DISCUSSION

This function provides an indication of whether a call to CD_CreateADSP will succeed or fail.

ERROR CODES

kCD_CDILNotInitialized
kCD_PlatformError
kCD_ServiceNotSupported
kCD_TCPCannotFindLibraryFns // these bottom three are only returned
kCD_TCPI nsufficientVersion // in the Windows version
kCD_TCPNoSockets

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CD_GetSerialPortName

`DIL_Error` CD_GetSerialPortName(`long index`, `char* buffer`, `long* bufLen`)

Returns a user-displayable C string containing the name of a selectable serial port.

<i>index</i>	A zero-based value indicating the port for which you want a string.
<i>buffer</i>	Where to store the C string. You may pass in NULL if you only want to query for the length of the string.
<i>bufLen</i>	When you call this function <i>*bufLen</i> should contain the number of bytes of the empty buffer. CD_GetSerialPortName sets this value to the number of bytes of the string that holds the port name, including the NULL terminator.
return value	An error code.

DISCUSSION

Normal usage of this function is to start with zero, incrementing *index*, until the function returns `kCD_IndexOutOfRange`.

ERROR CODES

`kCD_CDILNotInitialized`
`kCD_PlatformError`
`kCD_IndexOutOfRange`
`kCD_BufferTooSmall`
`KDIL_InvalidParameter`

CD_CreateADSP

`DIL_Error` CD_CreateADSP (`CD_Handle* pipe`, `const char* name`, `const char* type`)

Creates an ADSP-based communications pipe.

<i>pipe</i>	Where to store the new pipe.
<i>name</i>	The name of the ADSP connection. This string is what appears in the Chooser list on the Newton OS device. If

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you pass `NULL` for this parameter, the CDIL uses a default name based on your desktop computer's preferences (for instance, on a Macintosh, it will use the strings specified in the File Sharing control panel).

type The connection type. This is searched for by the Chooser on the Newton OS device. If you pass `NULL` for this parameter, the CDIL uses the type specified by the Connection/Dock application.

return value An error code.

SPECIAL CONSIDERATIONS

ADSP pipes are only available on the Mac OS platform.

ERROR CODES

`kCD_CDILNotInitialized`
`kCD_PlatfomError`
`kCD_ServiceNotSupported`
`kDIL_InvalidParameter`
`kDIL_OutOfMemory`

CD_CreateCTB

`DIL_Error CD_CreateCTB (CD_Handle* pipe, const char* toolName, const char* configString)`

Creates a Macintosh Communication Toolbox-based communications pipe.

pipe Where to store the new pipe.

toolName The name of the communication tool.

configString A tool-dependent configuration string.

return value An error code.

SPECIAL CONSIDERATIONS

Comm toolbox based pipes are only available on the Mac OS platform. See the Comm Toolbox documentation for valid configuration strings.

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ERROR CODES

kCD_CDILNotInitialized
kCD_PlatformError
kCD_ServiceNotSupported
kDIL_InvalidParameter
kDIL_OutOfMemory

CD_CreateMNPSerial

DIL_Error CD_CreateMNPSerial (CD_Handle* *pipe*, long *port*, long *baud*);

Creates a serial communications pipe based on the MNP protocol.

pipe Where to store the new pipe.
port The serial port to use.
baud The baud rate to communicate at in bytes per second.
Possible values are listed in Table 2-1.
return value An error code.

DISCUSSION

MNP is a packet-based protocol that ensures delivery of your data using compression and error correction.

Table 2-1 Possible baud rates for MNP serial connection

Windows

110	300	600	1200	2400
4800	9600	14400	19200	38400
5600	57600	115200	128000	256000

Macintosh

110	300	1200	2400	4800
9600	19200	38400	57600	

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Note

Not all of these baud rates are compatible with current Newton OS devices. They merely represent what is possible on the desktop platform. ♦

ERROR CODES

kCD_CDILNotInitialized
kCD_PlatformError
kCD_ServiceNotSupported
kDIL_InvalidParameter
kDIL_OutOfMemory

CD_CreateTCP

DIL_Error CD_CreateTCP(CD_Handle* *pipe*, long *port*)

Creates a TCP-based communications pipe.

<i>pipe</i>	Where to store the new pipe.
<i>port</i>	The TCP port to listen on. Note that once the connection is made, data transfer actually occurs on a different, randomly chosen, port. This frees up the port specified in this parameter for future connections.
return value	An error code.

ERROR CODES

kCD_CDILNotInitialized
kCD_PlatformError
kDIL_InvalidParameter
kDIL_OutOfMemory
kCD_TCPcantFindLibraryFns // these bottom three are only returned
kCD_TCPInsufficientVersion // in the Windows version
kCD_TCPNoSockets

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CD_Dispose

DI L_Error CD_Dispose(CD_Handle *pipe*)

Disposes of a communications pipe created by CD_CreateADSP, CD_CreateMNPSerial, CD_CreateCTB, **or** CD_CreateTCP.

pipe The pipe to dispose of.

return value An error code.

DISCUSSION

The pipe passed to CD_Dispose can be in any state. If appropriate, the pipe is disconnected or removed from a listening state before it is deleted.

After this call, the reference to the pipe is invalid and should no longer be used.

ERROR CODES

kCD_CDILNotInitialized
kCD_PlatformError
kDI L_InvalidParameter
kDI L_InvalidHandle

CD_Disconnect

DI L_Error CD_Disconnect(CD_Handle *pipe*)

Puts the specified pipe in the kCD_Disconnected **state.**

pipe The pipe to disconnect.

return value An error code.

DISCUSSION

If the pipe is listening, it stops listening. If the pipe is connected, it is disconnected. In all cases, the state of the pipe after making this call is kCD_Disconnected. Any internally buffered data is flushed and can no longer be read with CD_Read.

ERROR CODES

kCD_CDILNotInitialized

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kCD_PlatformError
kCD_BadPipeState
kCD_TimeOut
kCD_PipeDisconnected
kDIL_InvalidParameter
kDIL_InvalidHandle

CD_StartListening

DIL_Error CD_StartListening(CD_Handle *pipe*)

Makes the pipe start listening for a connection for a Newton device.

pipe The pipe to start listening.

return value An error code.

DISCUSSION

After the successful completion of this call, the pipe is put in the kCD_Listening **state**.

ERROR CODES

kCD_CDILNotInitialized
kCD_PlatformError
kCD_BadPipeState
kCD_TimeOut
kCD_PipeDisconnected
kDIL_InvalidParameter
kDIL_InvalidHandle

CD_Accept

DIL_Error CD_Accept(CD_Handle *pipe*)

Makes the pipe accept a pending connection.

pipe The pipe to accept the connection on. This pipe should be in the kCD_ConnectPending **state**.

return value An error code.

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DISCUSSION

After the successful completion of this call, the pipe is fully connected, its state will be `kCD_Connected`, and it can be used to exchange data with a Newton OS application.

ERROR CODES

`kCD_CDILNotInitialized`
`kCD_PlatformError`
`kCD_BadPipeState`
`kCD_TimeOut`
`kCD_PipeDisconnected`
`kDIL_InvalidParameter`
`kDIL_InvalidHandle`

CD_Read

`DIL_Error CD_Read(CD_Handle pipe, void* p, long count)`

Reads bytes from a pipe.

<i>pipe</i>	The pipe to read data from.
<i>p</i>	A pointer to the data buffer.
<i>count</i>	The number of bytes to read from the pipe.
return value	An error code.

DISCUSSION

Note that a pipe need not be connected in order for bytes to be read from it. It is possible for a pipe to have buffered data received from a Newton OS device before the connection was broken. As long as the pipe's state is `kCD_Connected` or `kCD_Disconnecting`, clients of the CDIL are still able to retrieve these bytes.

ERROR CODES

`kCD_CDILNotInitialized`
`kCD_PlatformError`
`kCD_BadPipeState`
`kCD_TimeOut`
`kCD_PipeDisconnected`
`kDIL_InvalidParameter`

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kDIL_InvalidHandle
kDIL_OutOfMemory

CD_BytesAvailable

DIL_Error CD_BytesAvailable(CD_Handle pipe, long* count)

Returns the number of bytes available for reading from the pipe.

<i>pipe</i>	The pipe.
<i>count</i>	A pointer to where the number of bytes available in the pipe should be stored by this function.
return value	An error code.

DISCUSSION

Note that a pipe need not be connected in order for bytes to be read from it. It is possible for a pipe to have buffered data received from a Newton device before the connection was broken. As long as the pipe's state is `kCD_Connected` or `kCD_DisconnectPending`, clients of the CDIL are still able to retrieve these bytes.

ERROR CODES

kCD_CDILNotInitialized
kCD_PlatformError
kCD_BadPipeState
kCD_TimeOut
kCD_PipeDisconnected
kDIL_InvalidParameter
kDIL_InvalidHandle
kDIL_OutOfMemory

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CD_Write

`DIL_Error CD_Write(CD_Handle pipe, const void* p, long count)`

Sends the given bytes to the Newton device.

<i>pipe</i>	The pipe to write data to.
<i>p</i>	A pointer to the data buffer.
<i>count</i>	The number of bytes to write to the pipe.
return value	An error code.

DISCUSSION

The data is not actually sent each time `CD_Write` is called. It is buffered until either the buffer is full, or a non-`CD_Write` call is executed: `CD_Idle`, `CD_Read`, `CD_Disconnect`, or `CD_BytesAvailable`.

ERROR CODES

`kCD_CDILNotInitialized`
`kCD_PlatformError`
`kCD_BadPipeState`
`kCD_TimeOut`
`kCD_PipeDisconnected`
`kDIL_InvalidParameter`
`kDIL_InvalidHandle`
`kDIL_OutOfMemory`

CD_FlushOutput

`DIL_Error CD_FlushOutput(CD_Handle pipe)`

Flushes any buffered data written to a pipe.

<i>pipe</i>	The pipe to flush.
return value	An error code.

DISCUSSION

To increase performance, the CDIL buffers all outgoing data. This data remains in the desktop computer until you call `CD_FlushOutput` to explicitly send to the Newton OS device. Otherwise, the data is implicitly sent on the

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next call to `CD_Idle`, `CD_Read`, `CD_Disconnect`, or `CD_BytesAvailable`. Note that the data could also be sent if the buffer is filled.

ERROR CODES

`kCD_CDILNotInitialized`
`kCD_PlatformError`
`kCD_BadPipeState`
`kCD_TimeOut`
`kCD_PipeDisconnected`
`kDIL_InvalidParameter`
`kDIL_InvalidHandle`
`kDIL_OutOfMemory`

CD_Idle

`DIL_Error CD_Idle(CD_Handle pipe)`

Allows the CDIL to service an open connection.

pipe The pipe to service.

return value An error code.

DISCUSSION

If the Newton device is sending data very rapidly, you must call this function frequently to buffer that data. The CDIL uses a dynamically sized buffer, but the underlying communication tool may use a statically sized one. If you don't call `CD_Idle` frequently enough, you may lose data. On the other hand, you unnecessarily slow down your application if you call this function too frequently. Frequencies on the order of a tenth of second should be adequate. In general you calling this function once each time through the main event loop, is sufficient.

ERROR CODES

`kCD_CDILNotInitialized`
`kCD_PlatformError`
`kCD_BadPipeState`
`kCD_TimeOut`
`kCD_PipeDisconnected`
`kDIL_InvalidParameter`
`kDIL_InvalidHandle`

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`kDIL_OutOfMemory`

CD_GetState

`CD_State CD_GetState(CD_Handle pipe)`

Updates and returns the state of the pipe.

pipe The pipe whose state you are interested in.

return value A state constant as listed in “CDIL States” (page 2-9).

DISCUSSION

There is no guarantee that two calls to `CD_GetState` made one right after the other will return the same value. In particular, the state can always change from `kCD_Listening` to `kCD_ConnectPending` or `kCD_DisconnectPending`, or from `kCD_Connected` to `kCD_DisconnectPending`.

CD_GetPlatformError

`long CD_GetPlatformError(CD_Handle pipe)`

Returns the platform-specific error code which caused another CDIL function to return `kCD_PlatformError`.

pipe The pipe on which the error occurred. This parameter can be `NULL` if the error occurred is not associated with a pipe, for example, if a `CD_CreateXXX` function failed.

return value A long value containing the platform specific error.

DISCUSSION

The CDIL functions call a wide variety of platform-specific transport functions to implement their functionality. If one of these functions returns an error, the CDIL function returns `kCD_PlatformError`. You can then, call `CD_GetPlatformError` to retrieve the actual error code.

ERROR CODES

A platform specific error
`kCD_CDILNotInitialized`

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CDIL Interface

CD_SetTimeout

`DIL_Error CD_SetTimeout (CD_Handle pipe, long timeoutInSecs)`

Sets the timeout period for `CD_Read` and `CD_Write` calls in a pipe.

<i>pipe</i>	The pipe whose timeout period is being set.
<i>timeoutInSecs</i>	The timeout period in seconds. The following constants are defined for you: <code>kCD_DefaultTimeout</code> for the default 30 second period, and <code>kCD_NoTimeout</code> if you want calls to <code>CD_Read</code> and <code>CD_Write</code> wait indefinitely.
return value	An error code.

DISCUSSION

When the CDIL pipe is created, it is initialized with a default timeout period of 30 seconds. This timeout period is used to control `CD_Read` and `CD_Write` calls (and, indirectly, any flushing of outgoing data). Timeout values are specified on a per-pipe basis.

For `CD_Read`, if the requested number of bytes are not available after the timeout period, a `kCD_Timeout` error is returned and no bytes will be transferred. For `CD_Write`, if no data can be sent after the timeout period, a `kCD_Timeout` error is returned.

The timeout does not occur, if the data is presently being transferred. That is, a long operation does not fail due to a timeout. Note that an attempt is made to send data even if the timeout is set to zero seconds.

ERROR CODES

`kCD_CDILNotInitialized`
`kCD_PlatformError`
`kCD_BadPipeState`
`kCD_TimeOut`
`kCD_PipeDisconnected`
`kDIL_InvalidParameter`
`kDIL_InvalidHandle`

CDIL Summary

Type Definitions

CD_Handle

Constants

CDIL States

kCD_Uninitialized
kCD_Disconnected
kCD_Listening
kCD_ConnectPending
kCD_Connected
kCD_DisconnectPending

Timeout Intervals

kCD_DefaultTimeout
kCD_NoTimeout

Error Codes

kDI_L_NoError
kDI_L_ErrorBase
kDI_L_OutOfMemory
kDI_L_InvalidParameter
kDI_L_InternalError
kDI_L_ErrorReadingFromPipe
kDI_L_ErrorWritingToPipe
kDI_L_InvalidHandle
kCD_ErrorBase
kCD_CDILNotInitialized
kCD_ServiceNotSupported
kCD_BadPipeState
kCD_Timeout

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kCD_PipeDisconnected
kCD_IndexOutOfRange
kCD_BufferTooSmall
kCD_PlatformError
kCD_TCPCantFindLibraryFns
kCD_TCPInsufficientVersion
kCD_TCPNoSockets

Functions

DILError CD_Startup()
DILError CD_Shutdown()
DILError CD_CheckADSP()
DILError CD_CheckCTB(const char* *toolName*)
DILError CD_CheckMNPSerial()
DILError CD_CheckTCP()
DILError CD_GetSerialPortName(long *index*, char* *buffer*, long* *bufLen*)
DILError CD_CreateADSP(CD_Handle* *pipe*, const char* *name*,
const char* *type*)
DILError CD_CreateCTB(CD_Handle* *pipe*, const char* *toolName*,
const char* *configString*)
DILError CD_CreateMNPSerial(CD_Handle* *pipe*, long *port*, long *baud*)
DILError CD_CreateTCP(CD_Handle* *pipe*, long *port*)
DILError CD_Dispose(CD_Handle *pipe*)
DILError CD_Disconnect(CD_Handle *pipe*)
DILError CD_StartListening(CD_Handle *pipe*)
DILError CD_Accept(CD_Handle *pipe*)
DILError CD_Read(CD_Handle *pipe*, void* *p*, long *count*)
DILError CD_BytesAvailable(CD_Handle *pipe*, long* *count*)
DILError CD_Write(CD_Handle *pipe*, const void* *p*, long *count*)
DILError CD_FlushOutput(CD_Handle *pipe*)
DILError CD_Idle(CD_Handle *pipe*)
CD_State CD_GetState(CD_Handle *pipe*)
long CD_GetPlatformError(CD_Handle *pipe*)
CD_Error CD_SetTimeout(CD_Handle *pipe*, long *timeoutInSecs*)

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CDIL Interface